

# THEORETICAL STUDIES OF THE VELOCITIES OF THE VIBRATIONS OF DRILL BITS WOODWORKING DRILLING MACHINES

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**Abstract:** On woodworking machines of the drilling group, drill bits of the following diameters (mm) are used at rotation speeds: SvP2 and SvA-2- $\varnothing$  50 mm,  $n = 3000$  rpm 4500 rpm; Sv8, Sv12- $\varnothing$  10-16 mm,  $n = 2800$  rpm; SGVP- $\varnothing$  up to 35 mm,  $n = 2800$  rpm. Acoustic models are described in detail in [1] as can be seen from the analytical dependences of sound pressure levels to calculate the noise spectra, it is necessary to determine the oscillation velocities of the drill bit at their natural frequencies.

**Keywords:** Woodworking machines, drill bit, noise, sound pressure

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## 1. INTRODUCTION

The 'spindle-drill bit' system is a rod system in which the drill bit is a cantilever part, and the spindle is a two-support beam. Bending stiffness of the drill bits of all diameters used in the range of single-and multi-spindle woodworking machines is much less than bending stiffness of the spindle. In addition, the sound energy of the spindle is radiated into the internal air volume of the spindle unit housing, which has significant sound insulation. Therefore, the contribution of the sound radiation of the spindle to the sound field at the operator's workplace can be ignored. Drill bits are also an open source of sound energy radiation, located in the immediate vicinity of the operators' workplaces. In this connection, the drill bits are approximated using a cylindrical radiator with a cantilever attachment [1-3].

## 2. THEORETICAL JUSTIFICATION OF CUTTING PARAMETERS

The force effect for drilling machines is determined according to the cutting mode standards for wood processing [4]. Drilling modes are shown in Tab. 1.

Wood species	Cutting speed, m/s	Feed, mm/rev
Soft wood	0.8 – 4	0.6 – 0.7
Hard wood	0.2 – 0.5	0.1 – 0.5

Tab.1: Drilling modes

The cutting power ( $W$ ) is determined using the formula:

$$N_p = \frac{KPD^2 u_0 n}{4 \cdot 60 \cdot 120} = 1,3 \cdot 10^{-4} D^2 u_0 n K_t \alpha_t \alpha_b \quad (1)$$

where

$D$  is the drill bit diameter, mm;  
 $n$  is the rotation speed, rpm;  
 $u_0$  is the feed, mm / rev;

$K_t$  is the specific cutting work,  $kg \cdot m/cm^3$ , set according to the table;

$\alpha_t$  is the coefficient that takes into account the type of wood;  
 $\alpha_b$  is a coefficient that takes into account the bluntness.

The average  $K_t$  value when drilling pine across the fibers is shown in Tab. 2.

Drilling diameter, mm	$K_t$ at the drill bit feed rate $u_0$ , mm/rev					
	1	0,7	0,4	0,3	0,2	0,1
5	8	8,5	8,8	9,6	12,4	20
10	4	4,2	4,4	4,8	6,2	10
15	3	3,2	3,4	3,6	4,2	7,5
20	2,4	2,5	2,6	2,9	3,6	6
25	2	2,1	2,2	2,4	3,1	5

Tab.2: Specific cutting work  $K_t$  (approximate) when drilling pine across the fibers with center drill bits with pruners

The value of the coefficient  $\alpha_t$  for different species: alder-0.9; beech-1.8; birch-1.2-1.5; oak-2.2.

The value of the coefficient  $\alpha_b$  for blunting the tool: the working time of the tool after sharpening

$h$	1	2	3	4	5	6
$\alpha_b$	1.2	1.3	1.35	1.4	1.45	1.5

The correction factor for the wood species is determined according to Tab. 3 (for pine,  $\alpha_t = 1$ ).

Linden, aspen	0.8	Birch	1.2-1.3
Spruce	0.9-1	Beech	1.3-1.5
Alder	1-1.05	Oak	1.5-1.6
Larch	1.1	Ash	1.5-2

Tab.3: The correction factor for the wood species

The specific cutting work is defined as the product of:  
 $K = K_t \cdot \alpha_t \cdot \alpha_b$

Cutting speed when drilling is determined using the dependence (m/s):

$$V_c = \frac{\pi d_a n}{2 \cdot 1000 \cdot 60}$$

where  
 $d_a$  is the drill diameter, m;

The amplitude of the cutting force when drilling is (n):

$$P = \frac{N}{V} = 3,8 K_t \cdot d_a \cdot u_0 \cdot \alpha_t \cdot \alpha_b$$

and the cutting force as a function of time  $P(t) = P \sin 0,2nt$ .

The oscillation velocities of the drill bit are determined from the differential equation.

$$EI \frac{\partial^4 Y}{\partial x^4} + m_0 \frac{\partial^2 Y}{\partial t^2} = P(t) \delta(x - x_0) \quad (1)$$

where  $E$  is the elastic modulus, Pa;

$I$  is the moment of inertia, m<sup>4</sup>;

$m_0$  is the distributed mass, kg/m;

$\delta(x-x_0)$  is the delta function centralized in the coordinate  $X_0$ .

Taking into account the elastic modulus and density of the drill bit material, the differential equation will take the form:

$$\frac{\partial^2 Y}{\partial t^2} + 2,7 \cdot 10^7 \frac{I}{F} \frac{\partial^4 Y}{\partial x^4} = \frac{P(t)}{7,8 \cdot 10^3 F} \delta(x - x_0) \quad (2)$$

where

$F$  is the cross-sectional area, m<sup>2</sup>.

### 3. THE MEASUREMENTS OF THE VELOCITY FLUCTUATIONS DRILLS

A comparison of the calculated values of the ratios of the values  $2,7 \cdot 10^7 \frac{I}{F}$  and  $1,7 \cdot 10^6 d_c^2$ : showed that for drill bits of different diameters, the difference does not exceed 10-12%. Therefore, for technical calculations of the sound pressure level spectra of drill bits, taking into account the setting of the function for the cantilever attachment:

$$\varphi(x) = \cos \frac{4\pi kx}{l_d} \cos \frac{2k-1}{2l_d} \pi x$$

the oscillation rates are determined from the system of differential equations:

$$\begin{aligned} \frac{d^2 Y_1}{dt^2} + 10^7 d_a^2 \left( \frac{10k-1}{l_d} \right)_{I_1}^4 &= \frac{2 \cdot 10^{-5}}{d_a^2 l_d} P \sin 0,2nt \\ \frac{d^2 Y_2}{dt^2} + 10^7 d_a^2 \left( \frac{6k+1}{l_d} \right)_{I_2}^4 &= \frac{2 \cdot 10^{-5}}{d_a^2 l_d} P \sin 0,2nt \\ \frac{d^2 Y_3}{dt^2} + 10^7 d_a^2 \left( \frac{6k-1}{l_d} \right)_{I_3}^4 &= \frac{3 \cdot 10^{-5}}{d_a^2 l_d} P \sin 0,2nt \\ \frac{d^2 Y_4}{dt^2} + 10^7 d_a^2 \left( \frac{2k+1}{l_d} \right)_{I_4}^4 &= \frac{3 \cdot 10^{-5}}{d_a^2 l_d} P \sin 0,2nt \\ \frac{d^2 Y_5}{dt^2} + 10^7 d_a^2 \left( \frac{2k-1}{l_d} \right)_{I_5}^4 &= \frac{6 \cdot 10^{-5}}{d_a^2 l_d} P \sin 0,2nt \end{aligned} \quad (3)$$

where

$d_d$  is the drill diameter, m;

$l_d$  is the drill length, m;

$n$  is speed of rotation, rpm.

The solutions of the equations with respect to the real part of the oscillation velocities are obtained in the following form:

$$\begin{aligned} v_{k1} &= Re \left\{ \frac{\partial Y_1}{\partial t} \right\} = \frac{4 \cdot 10^{-6} P n}{d_a^2 l_d} \sum_{k=1}^{k'} \left[ 10^7 d_a^2 \left( \frac{10k-1}{l_d} \right)^4 - (0,2n)^2 \right] \times \\ &\times \left\{ \left[ 10^7 d_a^2 \left( \frac{10k-1}{l_d} \right)^4 - (0,2n)^2 \right]^2 + 10^{14} d_a^2 \eta^2 \left( \frac{10k-1}{l_d} \right)^8 \right\}^{-1} \cos 0,2nt \\ v_{k2} &= Re \left\{ \frac{\partial Y_2}{\partial t} \right\} = \frac{4 \cdot 10^{-6} P n}{d_a^2 l_d} \sum_{k=1}^{k'} \left[ 10^7 d_a^2 \left( \frac{6k+1}{l_d} \right)^4 - (0,2n)^2 \right] \times \\ &\times \left\{ \left[ 10^7 d_a^2 \left( \frac{6k+1}{l_d} \right)^4 - (0,2n)^2 \right]^2 + 10^{14} d_a^2 \eta^2 \left( \frac{6k+1}{l_d} \right)^8 \right\}^{-1} \cos 0,2nt \\ v_{k3} &= Re \left\{ \frac{\partial Y_3}{\partial t} \right\} = \frac{1,6 \cdot 10^{-5} P n}{d_a^2 l_d} \sum_{k=1}^{k'} \left[ 10^7 d_a^2 \left( \frac{6k-1}{l_d} \right)^4 - (0,2n)^2 \right] \times \\ &\times \left\{ \left[ 10^7 d_a^2 \left( \frac{6k-1}{l_d} \right)^4 - (0,2n)^2 \right]^2 + 10^{14} d_a^2 \eta^2 \left( \frac{6k-1}{l_d} \right)^8 \right\}^{-1} \cos 0,2nt \\ v_{k4} &= Re \left\{ \frac{\partial Y_4}{\partial t} \right\} = \frac{1,6 \cdot 10^{-5} P n}{d_a^2 l_d} \sum_{k=1}^{k'} \left[ 10^7 d_a^2 \left( \frac{2k-1}{l_d} \right)^4 - (0,2n)^2 \right] \times \\ &\times \left\{ \left[ 10^7 d_a^2 \left( \frac{2k-1}{l_d} \right)^4 - (0,2n)^2 \right]^2 + 10^{14} d_a^2 \eta^2 \left( \frac{2k-1}{l_d} \right)^8 \right\}^{-1} \cos 0,2nt \\ v_{k5} &= Re \left\{ \frac{\partial Y_5}{\partial t} \right\} = \frac{1,2 \cdot 10^{-5} P n}{d_a^2 l_d} \sum_{k=1}^{k'} \left[ 10^7 d_a^2 \left( \frac{2k-1}{l_d} \right)^4 - (0,2n)^2 \right] \times \\ &\times \left\{ \left[ 10^7 d_a^2 \left( \frac{2k-1}{l_d} \right)^4 - (0,2n)^2 \right]^2 + 10^{14} d_a^2 \eta^2 \left( \frac{2k-1}{l_d} \right)^8 \right\}^{-1} \cos 0,2nt \end{aligned} \quad (4)$$

The maximum values of the oscillation velocity, i.e. [5-8], are used to calculate the sound pressure levels.

$$V_k = \sum_1^5 V_{ki}$$

### 4. CONCLUSION

In this way, the parameters of the cutting speed and the vibration of the drills during drilling were theoretically justified. The obtained dependences take into account the geometric dimensions of the cutting tool, the physical and mechanical properties and, most importantly, the parameters of the technological process when drilling workpieces from various types of wood.

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